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Fire in forests brings a lot of damage and loss to the forest system and human beings. Every year about millions of fires take place in forest, the fire areas cover million hectares and cause great damage and loss to forest system. Thus fire monitoring will be the effective tool for fire management. The fire monitoring and precaution system consist of three parts, fire detector, zigbee transmission device, monitoring center. The fire detector includes smoke detector, combustible gas detector, temperature detector, which is suitable for capturing and recording the status data of the area in real time. Four-Faith ZigBee communication device F8914 ZigBee modem is used as the wireless module to connect with detector and make up the wireless network based on zigbee protocol to realize the real time transmission. And then the data will be sent to the ZigBee + DTU device F8114, in this way, the data will be sent to the monitoring center by gprs. ZigBee terminal will transfer the data to the forest monitoring center, then the monitoring center will show the status on the LED display. Features of ZigBee 1. Wireless, reduce the complexity of the cable connection 2. Low cost, the ZigBee protocol is simple, there is no cost due to the communication flow 3. Intelligent, each node will search and set up the connection 4. Support start, tree and grid network topology, strong ability of network connection, can support 65000 nodes 5. In non obstacle environment, the distance of ZigBee is 2000 meters. We try our best to reach each and every corner of India using a few of the best courier services running in the Country such as FedEx, Delhivery, DTDC, BlueDart, XpressBees, Ecom Express, etc. as per the feedback for the courier partner at the customer's location. Few of the interior parts of India which are not covered by these courier services are covered by India-Post by us. We apply our best effort on daily basis to dispatch the order the same day it is ordered or within the next 24 hours of the order placed. Most of the orders that are placed before 1 PM are dispatched and shipped the same day. The orders placed post that is scheduled for next day shipment. The same effort is applied throughout the week including weekdays and sometimes weekends and public holidays as well. We facilitate local pickup (self-pickup for the local customers) on the weekdays and partially on weekends also. Download Project Document/Synopsis Gas Leakage and eventual fire accidents can be avoided from making a huge damage if we have systems installed that can detect gas leakage or fire at the earliest and notify to the respective authority to act upon it. This project using some sensors and wireless communication achieves this feat of detecting the occurrences of such events and notify the authorities present at the premises so that the damage incurred in life or property can be minimized or literally be avoided. The system consists of fire and gas sensors for detection purpose. If system detects a gas leakage the system first shuts off the gas supply (displayed using stepper motor) to avoid more gas leakage. The system now also starts an exhaust fan to suck out all the leaked gas. Also the system sends information of this event to the authorized user through a ZigBee wireless interface to the other ZigBee equipped project board. The other board thus receiving this information displays it on the LCD and also raises an alarm so that the user can get aware of the situation. Now the system also has a fire sensor to detect fires. As soon as a fire is detected, the system shuts off gas supply thus preventing the fire from spreading further and avoiding any chances of explosions. Now the system starts the exhaust fan too in order to suck out all the smoke, so any person stuck in the fire can see easily and escape it. Also it sends information of this event to the authorized user so user can take necessary action urgently. In this way ZigBee Based Fire Detection System is an effective system which can deal with emergency situations of explosive gas leakage or fire outbreak in a premises. Hardware Specifications Atmega Microcontroller GSM Module Xbee Module LPG CNG Gas Sensor Temperature Sensor LCD Display Crystal Oscillator Resistors Capacitors Transistors Cables and Connectors Diodes PCB and Breadboards LED Transformer/Adapter Push Buttons Switch IC IC Sockets Software Specifications Arduino Compiler MC Programming Language: C Block Diagram Download Project Document/Synopsis Many of the electronic appliances use an 12VDC, and if its portable appliance it... Download Project Document/Synopsis Drones are capable of highly advanced surveillance, and drones already in use by enforcement... 1. 1 FOREST FIRE DETECTION USING XBEE Submitted in partial fulfillment of Requirement For the Award of the Degree of Bachelor of Technology In Electronics and Communication Engineering Under the Sincere Guidance of Mr. Praveen Kumar Ms. Maninder Kaur Ms. Deepali Sharma Submitted By AMRIT SINGH(03913202810) TALVINDER SINGH(04013202810) Department of Electronics and Communication Engineering GURU TEGH BAHADUR INSTITUTE OF TECHNOLOGY G-8 Area RAJOURI GARDEN, NEW DELHI - 110064 (Affiliated to GURU GOBIND SINGH INDRAPRASTHA UNIVERSITY, DWARKA) 2. 2. 3. 3 DECLARATION This is to certify that the report entitled "FOREST FIRE DETECTION USING XBEE" which is submitted by us in partial fulfillment of requirement for the award of degree of B.Tech in Electronics & Communication Engineering to Guru TeghBahadur Institute of Technology, New Delhi comprises of our original work and due acknowledgment has been made in the text to all our other material used under the supervision of our guides. Date: TALVINDER SINGH(04013202810) AMRIT SINGH(03913202810) 4. 4 CERTIFICATE This is to certify that report entitled "FOREST FIRE DETECTION USING XBEE" Submitted By TALVINDER SINGH AMRIT SINGH in partial fulfillment of requirement for the award of degree of Bachelor of Technology In Electronics and Communication Engineering Guru Tegh Bahadur Institute of Technology, New Delhi is the record of candidates' own work carried out by them under our supervision. The matter embodied in this report is original and has not been submitted for the reward of any other degree. PRAVEEN KUMAR MANINDER KAUR (Project Guide) (Project Guide) Prof. VANEET SINGH (H.O.D. ECE) 5. 5 ACKNOWLEDGEMENT It brings us immense pleasure to finally complete the major project in partial fulfillment of requirement for the award of degree of B.Tech. We extend our sincere gratitude to Mrs. ROMINDER KAUR, Director, Prof. GURMEET SINGH SONI, Director General, and Mr. VANEET SINGH, Head of Department (ECE GTBIT) for providing us this opportunity to complete major project. We also pay our sincere gratitude to Mr. PRAVEEN KUMARand Mrs. MANINDER KAUR for their guidance to complete the project. We would also like to thank all the staff members of the Project Laboratory for contributing to the most pleasant working environment. Last but not the least, we would like to thank our friends from whom we learned and discovered many novel aspects about our project through the innumerable discussions we had and timely help they have provided. TALVINDER SINGH(04013202810) AMRIT SINGH(03913202810) 6. 6 TABLE OF CONTENTS CHAPTER 1 Introduction 1.1 What is fire fighting 1.2Block Diagram 1.3Components Used 1.4 Zigbee introduction 7. 7 ABSTRACT Components can be responsive, particularly compared to Bluetooth wake-up delays, which are typically around three seconds. Because ZigBee nodes can sleep most of the time, average power consumption can be low, resulting in long battery life. 1.4.1 NODE TYPES: The ZigBee standard has the capacity to address up to 65535 nodes in a single network. However, there are only three general types of node: 1)Coordinator 2)End Device 3)Router. These roles described below exist at the network level - a ZigBee node may also be performing tasks at the application level independent of the role it plays in the network. For instance, a network of ZigBee devices measuring temperature may have a temperature sensor application in each node, irrespective of whether they are End Devices, Routers or the Co-ordinator. These node types are described below. ZigBeeCoordinator(ZC): The most capable device, the coordinator forms the root of the network tree and might bridge to other networks. There is exactly one ZigBee coordinator in 14. 14 each network since it is the device that started the network originally. It is able to store information about the network, including acting as the Trust Centre & repository for security keys. All ZigBee networks must have one (and only one) Co-ordinator, irrespective of the network topology. In the Star topology, the Co-ordinator is the central node in the network. 1)In the Tree and Mesh topologies, the Co-ordinator is the top (root) node in the network. 2)This is illustrated below, where the Co-ordinator is colour-coded in dark black. At the network level, the Co-ordinator is mainly needed at system initialisation. The tasks of the Co-ordinator at the network layer are: 1)Selects the frequency channel to be used by the network (usually the one with the least detected activity) 2)Starts the network 3)Allows other devices to connect to it (that is, to join the network) The Co-ordinator can also provide message routing (for example, in a Star network), security management and other services. In some circumstances, the network will be able to operate normally if the Co-ordinator fails or is switched off. This will not be the case if the Co-ordinator provides a routing path through the network (for instance, in a Star topology, where it is needed to relay messages). Similarly the Co-ordinator provides services at the Application layer and if these services are being used (for example, Co-ordinator binding), the Co-ordinator must be able to provide them at all times. 15. 15 ZigBee Router (ZR): As well as running an application function a router can act as an intermediate router, passing data from other devices. Networks with Tree or Mesh topologies need at least one Router. The main tasks of a Router are: 1)Relays messages from one node to another 2)Allows child nodes to connect to it In a Star topology, these functions are handled by the Co-ordinator and, therefore, a Star network does not need Routers. In Tree and Mesh topologies, Routers are located as follows: 1)In a Tree topology, Routers are normally located in network positions that allow messages to be passed up and down the tree. 2)In a Mesh topology, a Router can be located anywhere that a message passing node is required. However, in all topologies (Star, Tree and Mesh), Router devices can be located at the extremities of the network, if they run applications that are needed in these locations - in this case, the Router will not perform its message relay function, unless in a corresponding pin of another XBee (see above). The possible positions of Routers in the different network topologies are illustrated below, where the Routers are color-coded in red: ZigBee End Device (ZED): Contains just enough functionality to talk to the parent node (either the coordinator or a router); it cannot relay data from other devices. This relationship 16. 16 allows the node to be asleep a significant amount of the time thereby giving long battery life. A ZED requires the least amount of memory, and therefore can be less expensive to manufacture than a ZR or ZC. End Devices are always located at the extremities of a network: 1)In the Star topology, they are perimeter nodes 2)In the Tree and Mesh topologies, they are leaf nodes This is illustrated below, where the End Devices are color-coded in light blue. (fig.1.4) The main tasks of an End Device at the network level are sending and receiving messages. Note that End Devices cannot relay messages and cannot allow other nodes to connect to the network through them. An End Device can often be battery-powered and, when not transmitting or receiving, can sleep in order to conserve power. 17. 17 CHAPTER 2 Hardware Description 2.1) XBEE Module 2.2)ATMEGA 16 2.3)Power Supply 2.4)Sensors 2.4.1)LM35 2.4.2)HR202 2.6)Crystal Oscillator 2.7)ISP Connector 2.8) Schematic Diagram 2.9)Interfacing ATMEGA and XBEE 18. 18 HARDWARE DESCRIPTION OF SYSTEM 2.1)XBEE MODULE: The Xbee Module(Fig 2.1) utilizes the IEEE 802.15.4 protocol which implements all of the above features. This protocol is known as a Low-Rate, Wireless Personal Area Network (LR-WPAN). It provides up to 250 kbps of data throughput between nodes on a CSMA/CA network. While not intended for large volumes of data, such as image files, it provides a means of moving data quickly between nodes for use in monitoring and control systems commonly referred to as a Wireless Sensor Network (WSN). In comparison to Bluetooth (IEEE 802.15.1), the LR-WPAN is designed as a much simpler protocol with lower data transfer rates (250 kbps compared to 1 Mbps). Bluetooth was designed as a replacement for peripheral cables and is used in communications between handheld devices, such as phones, requiring access security and high rates of data transfer. 19. 19 The XBee, using the IEEE 802.15.4 protocol, incorporates the following for communications and control on the WSN (wireless sensor network). Clear Channel Assessment (CCA): Before transmitting, an XBee node listens to see if the selected frequency channel is busy. 1) Addressing: The XBee has two addressing options: a fixed 64-bit serial number (MAC address) which cannot be changed, and a 16-bit assignable address (which we will use) that allows over 64,000 addresses on a network. 2) Error Checking and Acknowledgements: The XBee uses a checksum to help ensure received data contains no errors. Acknowledgements are sent to the transmitting node to indicate proper reception. Up to 3 retries are performed by default if acknowledgements are not received. 2.1.1 ) Pin description DOUT and DIN: These are the pins through which serial data is received by our controller or PC (DOUT) and sent to the XBee (Din). This data may be either for transmission between XBee modules or for setting and reading configuration information of the XBee. The default data rate is 9600 baud (bps) using asynchronous serial communications. 1) RESET: A momentary low on this pin will reset the XBee to the saved configuration settings. 2) CTS/RTS/DTR: These are used for handshaking between the XBee and your controller or the PC. The XBee will not send data out through the DOUT line to your controller unless the RTS line is held low. This allows the controller to signal to the XBee that it is ready to receive more data. DTR is typically used by the XBee when downloading new firmware, and therefore firmware updates can only be done using XBee adapter boards such as the Parallax USB Adapter Board that implement this connection. When transmitting, the XBee can signal to the controller through the CTS line that it is ready to send more data. CTS is seldom needed because the XBee sends data out by radio much more quickly than it accepts data from the controller. 3) DIO0-DIO7/D008: These are used as standard 3.3 V digital inputs and outputs. The XBee can be controlled to set the state of the pins. They can also be used in "line passing" so that the state of a pin on one XBee (high or low) is reflected on the corresponding pin of another 20. 20 4) A0 to AD6: These are 10-bit Analog to Digital Converter (ADC) inputs to the XBee. While we cannot directly read these values, some can also be used in "line passing" so that the amount of voltage on a pin on one XBee is reflected by the amount of voltage (PWM) on the corresponding pin of another XBee. 5) RSSI: The XBee can report the strength of the received RF signal as PWM output on this pin. This value can also be retrieved using AT commands or as part of a packet in API Mode. 2.2) ATMEGA 16 21. 21 ATmega16 (Fig3.1) is an 8-bit high performance microcontroller of Atmel's Mega AVR family with low power consumption. Atmega16 is based on enhanced RISC (Reduced Instruction Set Computing). Most of the instructions execute in one machine cycle. Atmega16 can work on a maximum frequency of 16MHz. ATmega16 has 16 KB programmable flash memory, static RAM of 1 KB and EEPROM of 512 Bytes. The endurance cycle of flash memory and EEPROM is 10,000 and 100,000, respectively. ATmega16 is a 40 pin microcontroller. There are 32 I/O (input/output) lines which are divided into four 8-bit ports designated as PORTA, PORTB, PORTC and PORTD. ATmega16 has various in-built peripherals like USART, ADC, Analog Comparator, SPI, JTAG etc. Each I/O pin has an alternative task related to in-built peripherals. The following table shows the pin description of ATmega16. Serial communication (Data receive) using AVR Microcontroller (ATmega16) USART: Communication between two entities is important for the information flow to take place. In general the information transport system can be parallel in which the complete byte of data is sent at a time, with each bit having a separate dedicated line or it can be serial where only one communication line is available which is shared by all the bits sequentially. The pros and cons of these two systems are equivalent and selection between the two depends on the application. Data can be exchanged using parallel or serial techniques. Setup for parallel data transfer is not cost effective but is a very fast method of communication. Serial communication is cost effective because it requires only a single line of connection but on the other hand is a slow process in comparison to parallel communication. This article explains serial communication of AVR microcontroller ATMEGA16 with PC. The data is transmitted from the controller using RS232 standard and displayed on the PC using Hyper Terminal. Microcontroller understands only digital language. However, the inputs available from the environment to the microcontroller are mostly analog in nature, i.e., they vary continuously with time. In order to understand the inputs by the digital processor, a device called analog to digital converter (ADC) is used. As the name suggests this peripheral gathers the analog information supplied from the environment and converts it to the controller understandable 22. 22 digital format, microcontroller then processes the information and provides the desired result at the output end. 23. 23 2.3)Power Supply Most of the MCUs available works off a 5v power supply except their low voltage versions. They need a clean and stable 5v power supply. This is achieved using the 7805 voltage regulator IC. We are using a Bridge Rectifier based Power supply (Fig3.2).Also the MCUs have a separate power supply for its analog parts to increase their accuracy and reduce noise. This must not be connected directly with the digital supply but connected via an LC network with the Vcc. Fig2.3( Bridge rectifier based Power Supply) 2.4) Sensors : 2.4.1) LM 35: 24 LM 35 is a precision centigrade Temperature sensor. The LM35 is an integrated circuit sensor that can be used to measure temperature with an electrical output proportional to the temperature (in °C) 2.4.2) General Description: The LM35 series are precision integrated-circuit temperature sensors, whose output voltage is linearly proportional to the Celsius (Centigrade) temperature. The LM35 thus has an advantage over linear temperature sensors calibrated in Kelvin, as the user is not required to subtract a large constant voltage from its output to obtain convenient Centigrade scaling. The LM35 does not require any external calibration or trimming to provide typical accuracies of ±14°C at room temperature and ±34°C over a full -55 to +150°C temperature range. Low cost is assured by trimming and calibration at the wafer level. The LM35's low output impedance, linear output, and precise inherent calibration make interfacing to readout or control circuitry especially easy. It can be used with single power supplies, or with plus and minus supplies. As it draws only 60 µA from its supply, it has very low self-heating, less than 0.1°C in still air. The LM35 is rated to operate over a -55° to +150°C temperature range, while the LM35C is rated for a -40° to +110°C range (-10° with improved accuracy). The LM35 series is available packaged in hermetic TO-46 transistor packages, while the LM35C, LM35CA, and LM35D are also available in the plastic TO-92 transistor package. The LM35D is also available in an 8-lead surface mount small outline package and a plastic TO- 220 package. 2.4.3)Features: Calibrated directly in ° Celsius (Centigrade) Linear + 10.0 mV/°C scale factor 0.5°C accuracy guaranteeable (at +25°C) (Fig 4.1 : Basic Centigrade Temperature Sensor +2 to +150 °C) 25. 25 (Fig4.2: Full-Range Centigrade Temperature Sensor) Choose R1 = -VS/50 µA V OUT=+1,500 mV at +150°C = +250 mV at +25°C = -550 mV at -55°C Maximum Ratings: Supply Voltage +35V to -0.2V Output Voltage +6V to -1.0V Output Current 10 mA Storage Temp.: TO-46 Package, -60°C to +180° 2.5)Humidity Sensor(HR 202): 1. HR202 is a new kind of humidity-sensitive resistor made from organic macromolecule materials, it can be used in occasions like: hospitals, storage, workshop, textile industry, tobaccos, pharmaceutical field, meteorology, etc. 2. Features: Excellent linearity, low power consumption, wide measurement range, quick response, anti-pollution, high stability, high performance-price ratio. 26. 26 3. Technical Specification: Operating range: humidity(20-95%RH) temperature(0-60Celsius) Power supply: 1.5V AC(Max sine) Operating frequency: 500Hz-2kHz Rated power: 0.2mW(Max sine) Central value: 31kΩ(at 25Celsius, 1kHz, 1V AC, 60%RH) Impedance range: 19.8-50.2kΩ (at 25Celsius, 1kHz, 1V AC, 60%RH) Accuracy: +-3%RH Hysteresis: +-1%RH Long-term stability: +-1%RH/year Response time:





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